

Lucy Diep, Sophya Yumakulov, Gregor Wolbring

ldiep@ucalgary.ca, syumakul@ucalgary.ca, gwolbrin@ucalgary.ca

Community Health Sciences; Community Rehabilitation and Disability Studies, Faculty of Medicine, University of Calgary

Purpose

To determine the impact of new communication technologies in the education system; whether it will affect the professional training of teachers and the prospects for disabled students with limited or no speech.

Background

New communication technologies are emerging, reshaping the way we interact with one another. They seem to improve the emotion and quality of life for disabled people^{2,9,14}.

New communication technologies include:

- Brain-machine interface (BMI) (Fig. 1)
- Sub-vocal speech device (Fig. 2)
- Social Robots (Fig. 3)
- iPad (Fig. 4)
- SmartBoard (Fig. 5)
- Speech generated communication device (Fig. 6)
- AlphaSmart (Fig. 7)

Methods

- Review of **Brain-machine interface (BMI)** and **educational assistant (EA)** in relation to disabled people literature
- Used Knowledge Share (KSv2) v2.1.3, developed by Dean Yergens (<http://people.ucalgary.ca/~dyergens/ksv2.htm>) to systematically review the literature
- Databases: ScienceDirect, Scopus, OVID(All), EBSCO(All), Web of Science, JSTOR
- As for **BMI**: 1,058 articles were found, however only 71 fulfilled the criteria (include: English, PDF available; exclude: pure technical, conference announcements, books); Kappa factor 0.99
- As for **EA**: 465 of the 840 articles found were included
- Used Atlas.ti 7.0.71 qualitative data analysis software

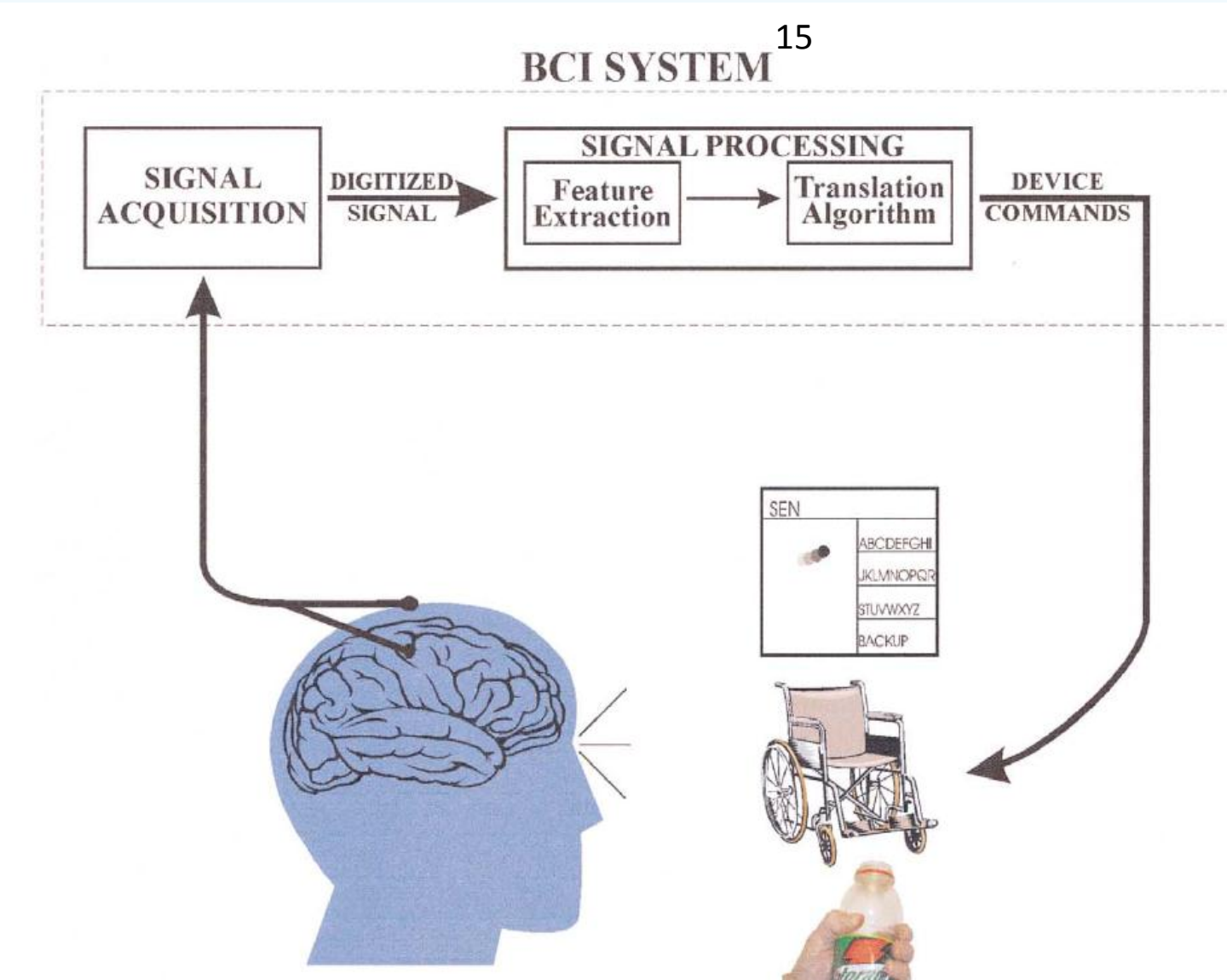


Fig. 1. Basic design and operation of any BCI system. Signals from the brain are acquired by electrodes on the scalp or in the brain and processed to extract specific signal features (e.g. amplitudes of evoked potentials or electroencephalic rhythms, firing rates of cortical neurons) that reflect the user's intent. These features are translated into commands that operate a device (e.g. a simple word processing program, a wheelchair, or a neuroprosthesis). Success depends on the interaction of two adaptive controllers, user and system. The user must develop and maintain good correlation between his or her intent and the signal features employed by the BCI, and the BCI must select and extract features that the user can control and must translate those features into device commands correctly and efficiently.



Fig. 2. Sub-vocal speech device¹⁷



Fig. 4. iPad¹⁸



Fig. 5. SmartBoard¹⁹



Fig. 6. Speech generated communication device²⁰



Fig. 7. AlphaSmart²¹

Issues: Example of BMI

- Invasive vs. Non-invasive technology and the debate within the scientific community:
 - **Invasive** (based on intracranial implantation)
 - Pro: provides neural signals of the best quality and has high potential for further improvement^{7,11,14}
 - Con: carries risk associated with invasive surgical procedures¹¹
 - **Non-invasive** (based on recordings of EEGs from the surface of the head)
 - Pro: provides solution for individuals without speech for simple communication with the outside world^{11,13}
 - Con: neural signals have a limited bandwidth^{11,13}
- Authenticity of the technology and of the individuals using the technology^{3,5}
- Safety – medical risks, privacy, data collection²
- Enhancements for minors and incompetent individuals^{3,5}
- Inequality to accessibility³

is research is made possible through the generous support of...

Technology & Educational Assistants

- Technology is described to be beneficial for greater success in student learning and an ameliorate for a lack of staff resource in the classroom¹
- With advancements in communication technology, there is a need for EAs to learn and effectively use the assistive technology⁴
- EAs perceive that they require more formal training when it comes to learning new technology¹²

Social Robotics in the Classroom

- Used as EAs - students receiving instructions^{12,15}
- Interacting and socializing with robots^{12,15}

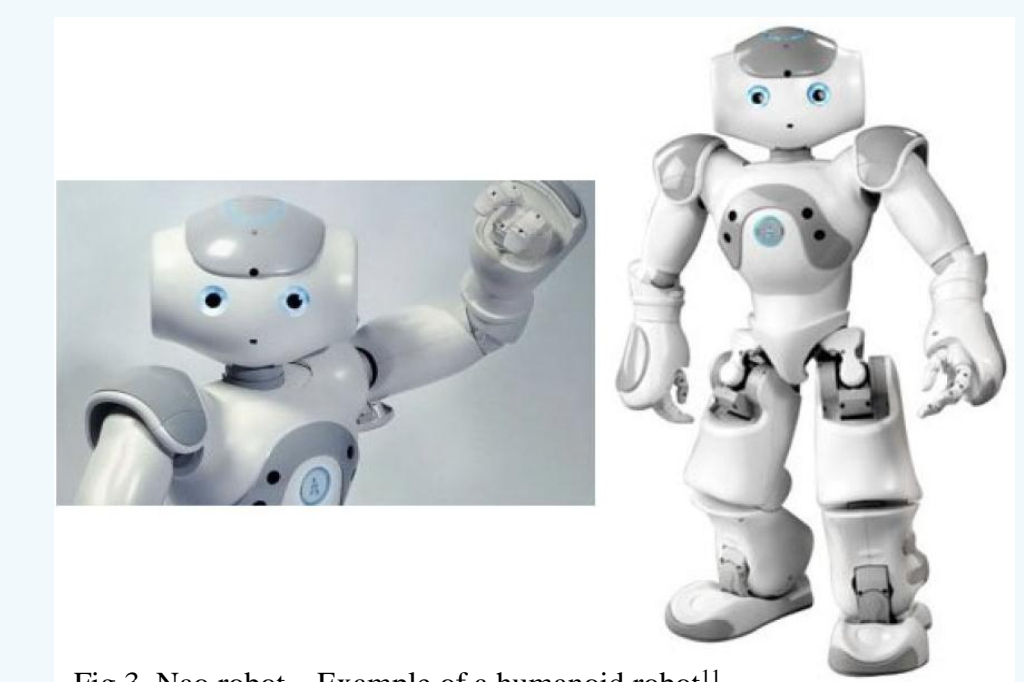


Fig. 3. Nao robot – Example of a humanoid robot¹¹

Future Directions

Research under way:

- Individual face-to-face interviews with a group of special education school teachers
- Online survey of a disability service organization in Saskatchewan

Research to be performed:

- Survey of disability service organization in Calgary
- Interview with: Speech Pathologists, university students from faculties of engineering/education/health sciences, high school students involved with summer research

References

- ¹American Council on Rural Special, E. n. (1985). *American Council on Rural Special Education (ACRES) Conference Proceedings (5th, Bellingham, Washington, March 19-22, 1985)*.
- ²Birbaumer, N. (2006). Breaking the silence: Brain-computer interfaces (BCI) for communication and motor control. *Psychophysiology*, 43(6), 517-532.
- ³Bostrom, N., & Sandberg, A. (2009). Cognitive enhancement: Methods, ethics, regulatory challenges. *Science and Engineering Ethics*, 15(3), 311-341.
- ⁴Brown, L., Farrington, K., Knight, T., Russ, C., & Ziegler, M. (1999). Fewer paraprofessionals and more teachers and therapists in educational programs for students with significant disabilities. *JOURNAL-ASSOCIATION FOR PERSONS WITH SEVERE HANDICAPS*, 24(4), 250-253.
- ⁵Clausen, J. (2011). Conceptual and ethical issues with brain-hardware interfaces. *Current Opinion in Psychiatry*, 24(6), 495.
- ⁶Coenen C, Schuijff M, Smits M, Klaassen P, Hennen L, Rader M, et al. Human Enhancement Study. European Parliament; 2009. Report No.: (IP/A/STOA/FWC/2005-28/SC35, 41 & 45) PE 417.483.
- ⁷Demetriades, A. K., Demetriades, C. K., Watts, C., & Ashkan, K. (2010). Brain-machine interface: The challenge of neuroethics. *The Surgeon : Journal of the Royal Colleges of Surgeons of Edinburgh and Ireland*, 8(5), 267-269. doi:10.1016/j.surge.2010.05.006
- ⁸Fukushi, T., Sakura, O., & Koizumi, H. (2007). Ethical considerations of neuroscience research: The perspectives on neuroethics in Japan. *Neuroscience Research*, 57(1), 10-16.
- ⁹Guenther, F. H., Brumberg, J. S., Wright, E. J., Nieto-Castanon, A., Tourville, J. A., Panko, M., . . . Andreassen, D. S. (2009). A wireless brain-machine interface for real-time speech synthesis. *PLoS One*, 4(12), e8218.
- ¹⁰Kochetkov, I. S., Hwang, B. Y., Appelbaum, G., Kellner, C. P., & Connolly Jr, E. S. (2010). Brain-computer interfaces: Military, neurosurgical, and ethical perspective. *Neurosurgical Focus*, 28(5), 25.
- ¹¹Lebedev, M. A., & Nicolelis, M. A. L. (2006). Brain-machine interfaces: Past, present and future. *Trends in Neurosciences*, 29(9), 536-546.
- ¹²Park, E., Kim, K., & del Pobil, A. (2011). The effects of a robot instructor's positive vs. negative feedbacks on attraction and acceptance towards the robot in classroom. *Social Robotics*, 135-141.
- ¹³Riggs, C. G. (2001). Ask the paraprofessionals: What are your training needs?. *Teaching Exceptional Children*, 33(3), 78-83.
- ¹⁴Tonnet, O., Marinelli, M., Citi, L., Rossini, P. M., Rossini, L., Megali, G., & Dario, P. (2008). Defining brain-machine interface applications by matching interface performance with device requirements. *Journal of Neuroscience Methods*, 167(1), 91-104.
- ¹⁵Wolpaw, J. R., Birbaumer, N., McFarland, D. J., Pfurtscheller, G., & Vaughan, T. M. (2002). Brain-computer interfaces for communication and control. *Clinical Neurophysiology*, 113(6), 767-791.
- ¹⁶Yun, S., Shin, J., Kim, D., Kim, C., Kim, M., & Choi, M. T. (2011). Engkey: Tele-education robot. *Social Robotics*, 142-152.
- ¹⁷<http://www.theaidoo.com/?action=technology>
- ¹⁸<http://thefix.com/faq/ios/>
- ¹⁹https://connect.mbps.org/groups/bpsolli/wiki/cb:95/SMART_Board_Resources.html
- ²⁰<http://teachinglearnerswithmultipleneeds.blogspot.ca/2008/05/funding-sources-for-aac.html>
- ²¹<http://en.wikipedia.org/wiki/AlphaSmart>